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On Construction and a Class of Non-Volterra Cubic Stochastic Operators

U.A. Rozikov 1* and A.Yu. Khamraev 2

¹ Institute of mathematics, 29, Do'rmon Yo'li str., 100125, Tashkent, Uzbekistan
 ² Qarshi filial of Tashkent University of Information Technology, Qarshi, Uzbekistan

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Abstract: We give a construction of a cubic stochastic operator (CSO) on a finite dimensional simplex. This construction depends on a probability measure μ which is given on a fixed finite graph G. Using the construction of CSO for μ defined as product of measures given on components of G a wide class of non-Volterra CSOs is described. It is shown that the non-Volterra operators can be reduced to N number (where N is the number of components) of Volterra CSOs defined on the components. By such a reduction we describe behavior of trajectories of a non-Volterra CSO defined on the three dimensional simplex.

Keywords: simplex; graph; cubic stochastic operator; Volterra cubic operator.

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1 Introduction

There are many systems which are described by nonlinear operators. One of the simplest nonlinear case is quadratic operator (for a recent review on the theory of quadratic stochastic operators see [5]). Quadratic dynamical systems have been proved to be a rich source of analysis for the investigation of dynamical properties and modeling in different domains, such as population dynamics [1, 6], physics [11], economy [2], mathematics [10]. In modern scientific investigations non-linear operators of higher order arise. In particular, a cubic stochastic operator (CSO) can be obtained in gene engineering and free population with a ternary production. To study non-linear dynamical systems a method of Lyapunov functions is used (see [5,9]).

^{*} Corresponding author: mailto:rozikovu@yandex.ru

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In [7], [8] and [12] the behavior of trajectories of some CSOs were studied. A CSO arises as follows: consider a population consisting of m species. Let $x^0 = (x_1^0, \ldots, x_m^0)$ be the probability distribution (where $x_i^0 = P(i)$ is the probability of $i, i = 1, 2, \ldots, m$) of species in the initial generation, and $P_{ijk,l}$ be the probability with which individuals in the *i*th, *j*th and *k*th species interbreed to produce an individual *l*, more precisely $P_{ijk,l}$ is the conditional probability P(l|i, j, k) with which *i*th, *j*th and *k*th species interbreed successfully, when they produce an individual *l*. In this paper we consider models of free population i.e., there is no difference of "sex" and in any generation the "parents" ijk are independent i.e., $P(i, j, k) = P(i)P(j)P(k) = x_i x_j x_k$.

Each CSO W can be uniquely defined by a matrix $\mathbf{P} \equiv \mathbf{P}(W) = \{P_{ijk,l}\}_{i,j,k,l=1}^{m}$. Usually the matrix \mathbf{P} is known. In this paper we give a constructive description of \mathbf{P} . This construction depends on a probability measure μ which is given on a fixed finite graph G and finite set of cells (configurations). Such constructions for quadratic stochastic operators are given in [3] and in the general form in [4].

The main aim of the paper is to show that if μ is the product of the probability measures being defined on the maximal connected subgraphs (components) then corresponding non-Volterra CSO can be reduced to N number (where N is the number of components) of Volterra operators defined on the components.

By such a reduction we describe behavior of trajectories of a non-Volterra CSO defined on the three dimensional simplex. These results are a natural generalization of the paper [13] which was devoted to quadratic stochastic operators.

2 Construction of Cubic Stochastic Operators

Recall that a CSO is a mapping of the simplex

$$S^{m-1} = \{x = (x_1, ..., x_m) \in R^m : x_i \ge 0, \sum_{i=1}^m x_i = 1\}$$

into itself, of the form

$$W: x'_{l} = \sum_{i,j,k=1}^{m} P_{ijk,l} x_{i} x_{j} x_{k}, \quad (l = 1, ..., m),$$
(1)

where $P_{ijk,l}$ are coefficients of 'heredity' and

$$P_{ijk,l} \ge 0, \quad \sum_{l=1}^{m} P_{ijk,l} = 1, \quad (i, j, k, l = 1, ..., m).$$
 (2)

Let $G = (\Lambda, L)$ be a finite graph without loops and multiple edges, where Λ is the set of vertexes and L is the set of edges of the graph.

Furthermore, let Φ be a finite set, called the set of alleles (in problems of statistical mechanics, Φ is called the range of spin). The function $\sigma : \Lambda \to \Phi$ is called a cell (in mechanics it is called configuration). Denote by Ω the set of all cells. Let $S(\Lambda, \Phi)$ be the set of all probability measures defined on the finite set Ω .

Let $\{\Lambda_i, i = 1, ..., N\}$ be the set of maximal connected subgraphs (components) of the graph G. For $\sigma \in \Omega$ denote by $\sigma(M)$ its "projection" (or "restriction") to $M \subset \Lambda$: $\sigma(M) = \{\sigma(x)\}_{x \in M}$. Then any $\sigma \in \Omega$ has the form $\sigma = (\sigma_1, \ldots, \sigma_N)$, where $\sigma_i = \sigma(\Lambda_i)$. We say $\sigma(M)$ is a subcell iff M is a maximal connected subgraph of G.

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Fix three cells $\sigma, \varphi, \psi \in \Omega$, and put

$$\Omega(\sigma,\varphi,\psi) = \{\tau = (\tau_1,\ldots,\tau_N) \in \Omega : \tau_i \in \{\sigma_i,\varphi_i,\psi_i\}, \forall i = 1,\ldots,N\}.$$

Remark 2.1 The set $\Omega(\sigma, \varphi, \psi)$ can be interpreted as the set of all possible 'children' of the 'parents' $\theta = (\sigma, \varphi, \psi)$. A child τ can be born from θ if it only consists the subcells of its parents θ . For quadratic stochastic operators such a set was first considered in [3] and in the general form in [4].

Now let $\mu \in S(\Lambda, \Phi)$ be a probability measure defined on Ω such that $\mu(\sigma) > 0$ for any cell $\sigma \in \Omega$. The heredity coefficients $P_{\sigma\varphi\psi,\tau}$ are defined as

$$P_{\sigma\varphi\psi,\tau} = \begin{cases} \frac{\mu(\tau)}{\mu(\Omega(\sigma,\varphi,\psi))}, & \text{if } \tau \in \Omega(\sigma,\varphi,\psi), \\ 0, & \text{otherwise.} \end{cases}$$
(3)

Obviously, $P_{\sigma\varphi\psi,\tau} \ge 0$, and $\sum_{\tau\in\Omega} P_{\sigma\varphi\psi,\tau} = 1$ for all $\sigma, \varphi, \psi \in \Omega$.

The CSO $W \equiv W_{\mu}$ acting on the simplex $S(\Lambda, \Phi)$ and determined by coefficients (3) is defined as follows: for an arbitrary measure $\lambda \in S(\Lambda, \Phi)$, the measure $W(\lambda) = \lambda' \in S(\Lambda, \Phi)$ is defined by the equality

$$\lambda'(\tau) = \sum_{\sigma,\varphi,\psi\in\Omega} P_{\sigma\varphi\psi,\tau}\lambda(\sigma)\lambda(\varphi)\lambda(\psi)$$
(4)

for any cell $\tau \in \Omega$.

The CSO construction is also closely related to the graph structure on the set $\Lambda.$

A CSO is called Volterra if the coefficients $P_{ijk,l}$ may be nonzero only when $l \in \{i, j, k\}$ and vanish in all the remaining cases (see [7,8]).

It is easy to see that any Volterra CSO has the following form

$$W: x_l' = x_l \left(x_l^2 + x_l \sum_{\substack{i=1\\i \neq l}}^m a_{i,l} x_i + \sum_{\substack{i,j=1\\i \neq l, \ j \neq l}}^m b_{ij,l} x_i x_j \right), \quad (l = 1, ..., m), \tag{5}$$

where $a_{i,l}$ and $b_{ij,l}$ are some coefficients depending on $P_{ijk,l}$.

Theorem 2.1 The CSO (4) is Volterra if and only if the graph G is connected.

Proof. Let G be connected then $\Omega(\sigma, \varphi, \psi) = \{\sigma, \varphi, \psi\}$. Consequently, by (3) it follows that the corresponding operator is Volterra. Conversely, if (3) satisfies $P_{\sigma\varphi\psi,\tau} = 0$, for $\tau \notin \{\sigma, \varphi, \psi\}$ then by condition $\mu(\sigma) > 0$ it follows that G is connected.

3 A Class of Non-Volterra CSOs

In this section we describe a condition on measure μ under which the CSO W_{μ} generated by μ (using the construction described in the previous section) can be studied using the theory of Volterra CSO.

Denote by $\Omega_i = \Phi^{\Lambda_i}$ the set of all cells defined on component Λ_i , i = 1, ..., N. Let μ_i be a probability measure defined on Ω_i , such that $\mu_i(\sigma) > 0$ for any $\sigma \in \Omega_i$, i = 1, ..., N.

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Consider probability measure μ on $\Omega = \Omega_1 \times \cdots \times \Omega_N$ defined as

$$\mu(\sigma) = \prod_{i=1}^{N} \mu_i(\sigma_i),\tag{6}$$

where $\sigma = (\sigma_1, ..., \sigma_N)$, with $\sigma_i \in \Omega_i, i = 1, ..., N$.

By Theorem 2.1, if N = 1 then QSO constructed on G is Volterra QSO.

Theorem 3.1 The CSO constructed by (3) with measure (6) is reducible to N separate Volterra CSOs.

Proof. For any $\sigma = (\sigma_1, ..., \sigma_N), \varphi = (\varphi_1, ..., \varphi_N), \psi = (\psi_1, ..., \psi_N) \in \Omega$ we have

$$\mu(\Omega(\sigma,\varphi,\psi)) = \sum_{\substack{\tau_1,\dots,\tau_N:\\\tau_i\in\{\sigma_i,\varphi_i,\psi_i\},i=1,\dots,N}} \prod_{i=1}^N \mu_i(\tau_i) = \prod_{i=1}^N \left(\mu_i(\sigma_i) + \mu_i(\varphi_i) + \mu_i(\psi_i)\right).$$

Using this equality by (3) we get

$$P_{\sigma\varphi\psi,\tau} = \begin{cases} \prod_{i=1}^{N} \frac{\mu_i(\tau_i)}{\mu_i(\sigma_i) + \mu_i(\varphi_i) + \mu_i(\psi_i)}, & \text{if } \tau \in \Omega(\sigma,\varphi,\psi), \\ 0 & \text{otherwise.} \end{cases}$$
(7)

Thus CSO generated by measure (6) can be written as

$$\lambda'(\tau) = \lambda'(\tau_1, ..., \tau_N) =$$

$$\sum_{\substack{= (\sigma_1, ..., \sigma_N) : \sigma_i \in \Omega_i \\= (\psi_1, ..., \psi_N) : \psi_i \in \Omega_i \\= (\psi_1, ..., \psi_N) : \psi_i \in \Omega_i}} \prod_{i=1}^N \frac{\mu_i(\tau_i) \mathbf{1}_{(\tau_i \in \{\sigma_i, \varphi_i, \psi_i\})}}{\mu_i(\sigma_i) + \mu_i(\varphi_i) + \mu_i(\psi_i)} \lambda(\sigma) \lambda(\varphi) \lambda(\psi).$$
(8)

Denote

$$X_{i,w} = \sum_{\substack{\tau \in \Omega: \\ \tau_i = w}} \lambda(\tau) = \sum_{\substack{\tau_1, \dots, \tau_{i-1}, \tau_{i+1}, \dots, \tau_N \\ \tau_k \in \Omega_k, k \neq i}} \lambda(\tau_1, \dots, \tau_{i-1}, w, \tau_{i+1}, \dots, \tau_N).$$
(9)

From (8) we have

 $\begin{array}{c} \sigma \\ \varphi \\ \psi \end{array}$

$$X_{i,w}' = \sum_{\substack{\tau \in \Omega:\\\tau_i = w}} \lambda'(\tau) = \sum_{\substack{\tau \in \Omega:\\\tau_i = w}} \left[\sum_{\substack{\sigma_1, \dots, \sigma_{i-1}, \sigma_{i+1}, \dots, \sigma_N\\\varphi, \psi \in \Omega}} \frac{\mu_i(w)}{\mu_i(w) + \mu_i(\varphi_i) + \mu_i(\psi_i)} \times \right]$$
$$\prod_{\substack{j=1\\j \neq i}}^N \frac{\mu_j(\tau_j) \mathbf{1}_{(\tau_j \in \{\sigma_i, \varphi_j, \psi_j\})}}{\mu_j(\sigma_j) + \mu_j(\varphi_j) + \mu_j(\psi_j)} \lambda(\sigma_1, \dots, \sigma_{i-1}, w, \sigma_{i+1}, \dots, \sigma_N) \lambda(\varphi) \lambda(\psi) + \sum_{\substack{\varphi_1, \dots, \varphi_i = 1, \varphi_{i+1}, \dots, \varphi_N\\\varphi_i, \psi \in \Omega}} \frac{\mu_i(w)}{\mu_i(\sigma_i) + \mu_i(w) + \mu_i(\psi_i)} \times$$

$$\prod_{\substack{j=1\\j\neq i}}^{N} \frac{\mu_{j}(\tau_{j})\mathbf{1}_{(\tau_{j}\in\{\sigma_{i},\varphi_{j},\psi_{j}\})}}{\mu_{j}(\sigma_{j})+\mu_{j}(\varphi_{j})+\mu_{j}(\psi_{j})}\lambda(\sigma)\lambda(\varphi_{1},...,\varphi_{i-1},w,\varphi_{i+1},...,\varphi_{N})\lambda(\psi)+ \\
\sum_{\substack{\psi_{1},...,\psi_{i-1},\psi_{i+1},...,\psi_{N}\\\sigma,\varphi\in\Omega}} \frac{\mu_{i}(w)}{\mu_{i}(\sigma_{i})+\mu_{i}(\varphi_{i})+\mu_{i}(\psi)}\times \\
\prod_{\substack{j=1\\j\neq i}}^{N} \frac{\mu_{j}(\tau_{j})\mathbf{1}_{(\tau_{j}\in\{\sigma_{i},\varphi_{j},\psi_{j}\})}}{\mu_{j}(\sigma_{j})+\mu_{j}(\varphi_{j})+\mu_{j}(\psi_{j})}\lambda(\sigma)\lambda(\varphi)\lambda(\psi_{1},...,\psi_{i-1},w,\psi_{i+1},...,\psi_{N})\Bigg] = \\
3\sum_{\substack{\sigma_{1},...,\sigma_{i-1},\sigma_{i+1},...,\sigma_{N}\\\varphi,\psi\in\Omega}} \frac{\mu_{i}(w)}{\mu_{i}(w)+\mu_{i}(\varphi_{i})+\mu_{i}(\psi_{i})}\times \\
\sum_{\substack{\tau\in\Omega:\\\tau_{j}=w}}\prod_{\substack{j=1\\j\neq i}}^{N} \frac{\mu_{j}(\tau_{j})\mathbf{1}_{(\tau_{j}\in\{\sigma_{j},\varphi_{j},\psi_{j}\})}}{\mu_{j}(\sigma_{j})+\mu_{j}(\varphi_{j})+\mu_{j}(\psi_{j})}\lambda(\sigma_{1},...,\sigma_{i-1},w,\sigma_{i+1},...,\sigma_{N})\lambda(\varphi)\lambda(\psi). \quad (10)$$

It is easy to see that

$$\sum_{\substack{\tau_1,\dots,\tau_{i-1},\tau_{i+1},\dots,\tau_N\\j\neq i}}\prod_{\substack{j=1\\j\neq i}}^N \frac{\mu_j(\tau_j)\mathbf{1}_{\{\tau_j\in\{\sigma_j,\varphi_j,\psi_j\}\}}}{\mu_j(\sigma_j)+\mu_j(\varphi_j)+\mu_j(\psi_j)} = 1.$$

Thus from (10) we have

RHS of
$$(10) =$$

$$3 \sum_{\substack{\sigma_1,\ldots,\sigma_{i-1},\sigma_{i+1},\ldots,\sigma_N\\\varphi,\psi\in\Omega}} \frac{\mu_i(w)}{\mu_i(w) + \mu_i(\varphi_i) + \mu_i(\psi_i)} \lambda(\sigma_1,\ldots,\sigma_{i-1},w,\sigma_{i+1},\ldots,\sigma_N)\lambda(\varphi)\lambda(\psi) = \sum_{\substack{\sigma,\varphi,\psi\\\sigma_i=\varphi_i=\psi_i=w}} \lambda(\sigma)\lambda(\varphi)\lambda(\psi) + 6 \sum_{\psi_i\in\Omega_i\setminus w} \frac{\mu_i(w)}{2\mu_i(w) + \mu_i(\psi_i)} \times \sum_{\substack{\sigma_1,\ldots,\sigma_{i-1},\sigma_{i+1},\ldots,\sigma_N\\\varphi_1,\ldots,\varphi_{i-1},\varphi_{i+1},\ldots,\varphi_N\\\psi_1,\ldots,\psi_{i-1},\psi_{i+1},\ldots,\psi_N} \lambda(\sigma_1,\ldots,\sigma_{i-1},w,\sigma_{i+1},\ldots,\sigma_N)\lambda(\varphi_1,\ldots,\varphi_{i-1},w,\varphi_{i+1},\ldots,\varphi_N)\lambda(\psi) + \dots$$

$$3 \sum_{\varphi_{i},\psi_{i}\in\Omega_{i}\setminus w} \frac{\mu_{i}(w)}{\mu_{i}(w) + \mu_{i}(\varphi_{i}) + \mu_{i}(\psi_{i})} \times \sum_{\substack{1,\sigma_{i+1},\ldots,\sigma_{N} \\ \downarrow \downarrow \varphi_{i+1},\ldots,\varphi_{N}}} \lambda(\sigma_{1},\ldots,\sigma_{i-1},w,\sigma_{i+1},\ldots,\sigma_{N})\lambda(\varphi)\lambda(\psi) =$$

 $\begin{aligned} &\sigma_1,...,\sigma_{i-1},\sigma_{i+1},...,\sigma_N\\ &\varphi_1,...,\varphi_{i-1},\varphi_{i+1},...,\varphi_N\\ &\psi_1,...,\psi_{i-1},\psi_{i+1},...,\psi_N \end{aligned}$

$$X_{i,w}^3 + \sum_{\psi \in \Omega_i \setminus w} \frac{6\mu_i(w)}{2\mu_i(w) + \mu_i(\psi)} X_{i,w}^2 X_{i,\psi} + \sum_{\varphi, \psi \in \Omega_i \setminus w} \frac{3\mu_i(w)}{\mu_i(w) + \mu_i(\varphi) + \mu_i(\psi)} X_{i,w} X_{i,\varphi} X_{i,\psi}.$$

Thus operator (8) can be rewritten as

$$X_{i,w}' = X_{i,w} \left(X_{i,w}^2 + \sum_{\psi \in \Omega_i \setminus w} \frac{6\mu_i(w)}{2\mu_i(w) + \mu_i(\psi)} X_{i,w} X_{i,\psi} + \sum_{\varphi,\psi \in \Omega_i \setminus w} \frac{3\mu_i(w)}{\mu_i(w) + \mu_i(\varphi) + \mu_i(\psi)} X_{i,\varphi} X_{i,\psi} \right),$$
(11)

where $X_{i,w}$ is defined by (9), $w \in \Omega_i, i = 1, ..., N$.

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Note that $\sum_{w \in \Omega_i} X_{i,w} = 1$ for any i = 1, ..., N. One can see that for each fixed i (i = 1, ..., N) the operator (11) is similar to (5), i.e. is a Volterra CSO $W^{(i)} : S^{|\Omega_i|-1} \to S^{|\Omega_i|-1}$. The theorem is proved.

This theorem allows us to use the theory of Volterra CSO to describe the behavior of trajectories of non-Volterra CSO (8).

If for each $i \in \{1, ..., N\}$ the asymptotical behavior of trajectories of CSO $W^{(i)}$ is known, say $X_{i,w}^{(n)} \to X_{i,w}^*$, $n \to \infty$, then asymptotical behavior of W (i.e. (8)), say $\lambda^{(n)}(\tau) \to \lambda^*(\tau), n \to \infty$, can be found from the following system of linear equations

$$\sum_{\in\Omega:\tau_i=w}\lambda^*(\tau) = X^*_{i,w}, \quad w \in \Omega_i, i = 1, ..., N.$$
(12)

In the following section we shall illustrate the restriction of a non-Volterra cubic stochastic operator to two Volterra operators and study the trajectory of the non-Volterra operator by these two Volterra operators.

4 An Example

Consider graph $G = (\Lambda, L)$ with $\Lambda = \{1, 2\}$ and $L = \emptyset$. Take $\Phi = \{1, 2\}$. Then non-Volterra CSO (8) has the form

$$\begin{split} x_1' &= x_1^3 + 3\beta_1(x_1^2x_2 + x_1x_2^2) + 3\alpha_1(x_1^2x_3 + x_1x_3^2) + \\ &\quad 3\alpha_1\beta_1[x_1^2x_4 + x_1x_4^2 + x_2^2x_3 + x_2x_3^2 + 2(x_1x_2x_3 + x_1x_2x_4 + x_1x_3x_4 + x_2x_3x_4)], \\ x_2' &= x_2^3 + 3\beta_2(x_1^2x_2 + x_1x_2^2) + 3\alpha_1(x_2^2x_4 + x_2x_4^2) + \\ &\quad 3\alpha_1\beta_2[x_1^2x_4 + x_1x_4^2 + x_2^2x_3 + x_2x_3^2 + 2(x_1x_2x_3 + x_1x_2x_4 + x_1x_3x_4 + x_2x_3x_4)], \\ x_3' &= x_3^3 + 3\alpha_2(x_1x_3^2 + x_1^2x_3) + 3\beta_1(x_3^2x_4 + x_3x_4^2) + \\ &\quad 3\alpha_2\beta_1[x_1^2x_4 + x_1x_4^2 + x_2^2x_3 + x_2x_3^2 + 2(x_1x_2x_3 + x_1x_2x_4 + x_1x_3x_4 + x_2x_3x_4)], \end{split}$$

$$\begin{aligned} x_4' &= x_4^3 + 3\alpha_2(x_2x_4^2 + x_2^2x_4) + 3\beta_2(x_3^2x_4 + x_3x_4^2) + \\ &\quad 3\alpha_2\beta_2[x_1^2x_4 + x_1x_4^2 + x_2^2x_3 + x_2x_3^2 + 2(x_1x_2x_3 + x_1x_2x_4 + x_1x_3x_4 + x_2x_3x_4)], \end{aligned}$$
(13)

where $\mu_1 = (\alpha_1, \alpha_2), \, \alpha_j > 0, \, \alpha_1 + \alpha_2 = 1; \, \mu_2 = (\beta_1, \beta_2), \, \beta_j \ge 0, \, \beta_1 + \beta_2 = 1.$

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Putting $x_1 + x_2 = X_{1,1}$, $x_3 + x_4 = X_{1,2}$ and $x_1 + x_3 = X_{2,1}$, $x_2 + x_4 = X_{2,2}$ we get the Volterra cubic operators:

$$X'_{1,1} = X_{1,1} \left(X^2_{1,1} + 3\alpha_1 X_{1,2} (X_{1,1} + X_{1,2}) \right),$$

$$X'_{1,2} = X_{1,2} \left(X^2_{1,2} + 3\alpha_2 X_{1,1} (X_{1,1} + X_{1,2}) \right),$$
(14)

and

$$X'_{2,1} = X_{2,1} \left(X^2_{2,1} + 3\beta_1 X_{2,2} (X_{2,1} + X_{2,2}) \right),$$

$$X'_{2,2} = X_{2,2} \left(X^2_{2,2} + 3\beta_2 X_{2,1} (X_{2,1} + X_{2,2}) \right).$$
(15)

Since $X_{i,1} + X_{i,2} = 1$, i = 1, 2, the study of both operators (14) and (15) can be reduced to the study of a dynamical system given by the function $f_{\alpha}(x) = x(x^2 + 3\alpha(1 - x))$, $x \in [0, 1]$. This is an increasing function of $x \in [0, 1]$ for each parameter $\alpha \in [0, 1]$.

We have

$$\operatorname{Fix}(f_{\alpha}) = \{x \in [0,1] : f_{\alpha}(x) = x\} = \begin{cases} \{0,1\}, & \text{if } \alpha \in [0,1/3] \cup [2/3,1], \\ \{0,3\alpha - 1,1\}, & \text{if } \alpha \in (1/3,2/3). \end{cases}$$

Using the above-mentioned properties of the function $f_{\alpha}(x)$ and checking $|f'_{\alpha}(a)|$ at $a \in \text{Fix}(f_{\alpha})$ one can see that the sequence $x^{(n)} = f_{\alpha}(x^{(n-1)}), n \ge 1$ for $x^{(0)} \in [0, 1]$ has the following limits

$$\lim_{n \to \infty} x^{(n)} = \begin{cases} 0, & \text{for any } x^{(0)} \in [0, 1), & \alpha \in [0, 1/3], \\ 3\alpha - 1, & \text{for any } x^{(0)} \in (0, 1), & \alpha \in (1/3, 2/3), \\ 1, & \text{for any } x^{(0)} \in (0, 1], & \alpha \in [2/3, 1]. \end{cases}$$
(16)

By equalities (16) for operators (14) we get the following

$$\lim_{n \to \infty} (X_{1,1}^{(n)}, X_{1,2}^{(n)}) = \begin{cases} (0,1), & \text{for any } X_{1,1}^{(0)} \in [0,1), & \alpha_1 \in [0,1/3], \\ (3\alpha_1 - 1, 2 - 3\alpha_1), & \text{for any } X_{1,1}^{(0)} \in (0,1), & \alpha_1 \in (1/3, 2/3), \\ (1,0), & \text{for any } X_{1,1}^{(0)} \in (0,1], & \alpha_1 \in [2/3,1]. \end{cases}$$

$$(17)$$

A similar formula is true for the operator (15), where α_1 is replaced by β_1 . Combining these formulas and using formula (12) one proves the following.

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Proposition 4.1 The trajectory of the non-Volterra CSO (13) has the following limit

$$\lim_{n \to \infty} x^{(n)} = \begin{cases} (1,0,0,0), & \text{if } \alpha_1, \beta_1 \in [2/3,1], \\ (0,1,0,0), & \text{if } \alpha_1 \in [2/3,1], \beta_1 \in [0,1/3], \\ (0,0,1,0), & \text{if } \alpha_1 \in [0,1/3], \beta_1 \in [2/3,1], \\ (0,0,0,1), & \text{if } \alpha_1, \beta_1 \in [0,1/3], \\ (0,0,3\beta_1 - 1,2 - 3\beta_1), & \text{if } \alpha_1 \in [0,1/3], \beta_1 \in (1/3,2/3), \\ (3\beta_1 - 1,2 - 3\beta_1,0,0), & \text{if } \alpha_1 \in [2/3,1], \beta_1 \in (1/3,2/3), \\ (0,3\alpha_1 - 1,0,2 - 3\alpha_1), & \text{if } \alpha_1 \in (1/3,2/3), \beta_1 \in [0,1/3], \\ (3\alpha_1 - 1,0,2 - 3\alpha_1,0), & \text{if } \alpha_1 \in (1/3,2/3), \beta_1 \in [2/3,1], \\ \in U, & \text{if } \alpha_1 \in (1/3,2/3), \beta_1 \in (1/3,2/3), \end{cases}$$

where

 $U = \{x \in S^3 : x_1 + x_2 = 3\alpha_1 - 1, x_3 + x_4 = 2 - 3\alpha_1, x_1 + x_3 = 3\beta_1 - 1, x_2 + x_4 = 2 - 3\beta_1\}.$

5 Concluding Remarks

In mathematical biology, the nonlinear operator W is called an evolution operator. The fixed points of W are interpreted as equilibrium states of the population, $\lambda \in S^{m-1}$ is called a state of the population, and $W(\lambda), W^2(\lambda), \ldots$ are called states of the population in subsequent generations (offsprings). Since W is a non-linear operator, the investigation of the sequence $W^n(\lambda)$ is a difficult problem in general. So one has to consider a particular case of W, for which the problem is respectively simple. In this paper to define such an operator, a construction of CSO on a finite dimensional simplex is given. Using the construction of CSO a wide class of non-Volterra CSOs is described. Then we have showed that the non-Volterra operators can be reduced to a finitely many of Volterra CSOs. By such a reduction we described behavior of trajectories of a non-Volterra CSO defined on the three dimensional simplex.

Here we shall give a biological interpretation of Proposition 4.1. Assume that the evolution of a certain biological system consisting of 4 types of individuals is described by operator (13). Using Proposition 4.1, we can conclude the following:

1. The biological system has up to 5 equilibrium states.

2. After a certain period of time, some types will be at the vanishing point.

3. If a system is in an equilibrium state, then, depending on the state, it can have only one of 1, 2, 3, 4 types.

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